

LEVEL I

## **AFATL-TR-80-108**

A Method to Calculate Uncertainties of Drag Coefficient Wind Tunnel Data

AIRCRAFT COMPATIBILITY BRANCH MUNITIONS DIVISION

Spence E Peters Jr, Capt, USAF

OCTOBER 1980

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#### **PREFACE**

This study was conducted by the Aircraft Compatibility Branch of the Munitions Division of the Air Force Armament Laboratory, Armament Division, Eglin Air Force Base, Florida.

This report has been reviewed by the Information Office (OI) and is releasable to the National Technical Information Service (NTIS). At NTIS, it will be available to the general public, including foreign nations.

This technical report has been reviewed and is approved for publication.

FOR THE COMMANDER

BARNES E. HOLDER, JR., Colonel, USAF

Chief, Munitions Division

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## LIST OF SYMBOLS

Α	AIRCRAFT MODEL REFERENCE AREA
$\mathbf{a}_0, \mathbf{a}_1, \mathbf{a}_2$	REGRESSION COEFFICIENTS USED TO FIT LIFT - DRAG DATA
CD	DRAG COEFFICIENT
$c_L$	LIFT COEFFICIENT
FA	MEASURED AXIAL FORCE
FN	MEASURED NORMAL FORCE
IM	ANGLE BETWEEN AIRCRAFT MODEL WATERLINE AND BALANCE AXIS
M	MACH NUMBER
Q	DYNAMIC PRESSURE
S	ESTIMATED SAMPLE STANDARD DEVIATION
s ( )	PRECISION INDEX
t <sub>n</sub>	nth PRECENTILE POINT FOR THE TWO TAILED, STUDENT "t" DISTRIBUTION
u (c <sub>D</sub> )	UNCERTAINTY IN DRAG COEFFICIENT
α	AIRCRAFT ANGLE OF ATTACK
β	AIRCRAFT ANGLE OF SIDESLIP
μ	TRUE MEAN VALUE OF A PARAMETER
ν	NUMBER OF DEGREES OF FREEDOM FOR A STATISTICAL TEST
σ	STANDARD DEVIATION

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# SECTION I INTRODUCTION

The effects of external store carriage on aircraft performance can be significant, especially for fighter aircraft carrying fuel tanks or air to ground weapons. Degradation in top speed and range must be accurately estimated to determine if a particular store configuration is practical from a mission standpoint. Flight testing can provide answers, but it is extremely expensive and time consuming. For this reason, only selected aircraft loadings are usually tested.

To estimate performance parameters for a greater number of configurations, wind tunnel test data are often used. A scale model of the clean aircraft and one with the aircraft loaded with the store configuration of interest is tested. Curves of lift versus drag coefficient are constructed, and the drag increment due to external stores is calculated for a particular flight condition, i.e., lift coefficient.

Because of the nature of any measurement process, an uncertainty is associated with the wind tunnel data. The total data uncertainty is a combination of uncertainties in tunnel test conditions, model positioning, and model instrumentation. Since the lift coefficient value for the flight condition of interest rarely appears as a test point, a fitted curve must be constructed from the data. This curve fit process is another source of possible uncertainty. This report investigates the uncertainty associated with wind tunnel drag data and presents a method that can be used to calculate it for a specific flight condition of interest.

#### SECTION II

#### GENERAL METHOD OF UNCERTAINTY CALCULATION

Uncertainty associated with  $C_{\overline{D}}$  at a given condition is caused by uncertainties in the measurement process and those induced by the curve fit procedure. This requires that the uncertainties associated with each factor be propagated to arrive at a final result. The method chosen here is the Taylor series method of error propagation.

A derivation of the Taylor series method can be found in Reference 1. Some of the assumptions used in the derivation are:

- 1. Response, Z, is defined as a function of the measured variables  $\mathbf{X}_1, \ \mathbf{X}_2, \ \ldots, \ \mathbf{X}_n$ .
- 2. Z is continuous in the neighborhood of  $\mu_{x_1}$ ,  $\mu_{x_2}$ , ...,  $\mu_{x_n}$ .  $\mu_{x_1}$ ,  $\mu_{x_2}$ , ...,  $\mu_{x_n}$  are the mean values associated with  $x_1$ ,  $x_2$ , ...,  $x_n$  which all have error distributions about the point of interest.
- 3. Z has continuous partial derivatives in the vicinity of  $\mu_{x_1}, \ \mu_{x_2}, \ \ldots, \ \mu_{x_n}$  .
  - 4.  $x_1, x_2, \ldots, x_n$  are independent of each other.
  - 5.  $(\mu_{x_1} x_1)$ ,  $(\mu_{x_2} x_2)$ , ...,  $(\mu_{x_n} x_n)$  are small or  $\frac{\partial^2 z}{\partial x_1^2}$ ,  $\frac{\partial^2 z}{\partial x_2^2}$ , ...,  $\frac{\partial^2 z}{\partial x_n^2}$  are small or zero.

The assumptions will be satisfied if the functions considered are restricted to smooth curves near the point of interest with no discontinuities and with higher order derivatives either small or zero.

The results of the derivation show that:

If

$$Z = f(x_1, x_2, ..., x_n)$$
 (1)

then

$$S(Z) = \{ \left[ \frac{\partial Z}{\partial x_1} \right]^2 + \left[ \frac{\partial Z}{\partial x_2} \right]^2 + \dots + \left[ \frac{\partial Z}{\partial x_n} \right]^2 \}^{\frac{1}{2}}$$
 (2)

where S(Z),  $S(X_1)$ ,  $S(X_2)$ , ...,  $S(X_n)$  are the precision indices of the response, Z, and the variables  $X_1$ ,  $X_2$ , ...,  $X_n$ . The precision index is the computed standard deviation of the measurements (i.e., random error). It is defined as

$$S = \begin{bmatrix} \frac{1}{n-1} & \sum_{i=1}^{n} (x_i - \bar{x})^2 \end{bmatrix}^{\frac{1}{2}}$$
 (3)

 $X_i$  and  $\bar{x}$  are, of course, the value of x of a particular point and the mean value of x, respectively. If the sample size is large, the precision index is approximately equal to the actual population standard deviation ( $\sigma$ ) associated with the random variable Z.

Depending on the confidence level attached to the response, the uncertainty is simply a function of the precision index or standard deviation.

This assumes that no bias or systematic errors are present. For drag increments caused by external stores, this is a reasonable assumption. The drag increments are calculated as differences between data taken during one test with the same model and instrumentation. While bias errors may be present, they are approximately equal for different model configurations. When the increment is determined, the bias errors should drop out. This assumption is of critical importance in the following discussions. It would not be true if raw data from separate tests were compared or if different instrumentation was used during one test.

For the case of interest,  $C_L$  and  $C_D$  are both random variables since both are measured during testing. With the assumption that measured values of  $C_L$  and  $C_D$  are normally distributed with mean values  $\mu_{C_L}$  and  $\mu_{C_D}$ , the uncertainty associated with  $C_D$  on the fitted  $C_L$  -  $C_D$  curve is found as follows.

Figure 1 shows a number of data points. From aerodynamic considerations,  $C_{\mathrm{D}}$  is considered a second order polynomial function of  $C_{\mathrm{L}}$ . That is:

$$C_D = a_0 + a_1 C_L + a_2 C_L^2$$
 (4)

Using the regression coefficients  $a_0$ ,  $a_1$ , and  $a_2$ , the values of  $C_D$  at the data point  $(C_{L_1})$  and the flight condition of interest  $(C_{L_2})$  can be found.

$$C_{D_1} = a_0 + a_1 C_{L_1} + a_2 C_{L_1}^2$$
 (5)

$$C_{D_2} = a_0 + a_1 C_{L_2} + a_2 C_{L_2}^2$$
 (6)

The difference between the values of  $C_{\rm D}$  is:

$$C_{D_2} - C_{D_1} = \Delta C_D = a_1 (C_{L_2} - C_{L_1}) + a_2 (C_{L_2}^2 - C_{L_1}^2)$$
 (7)  
 $C_{D_2}$  can be redefined in terms of  $C_{D_1}$  and  $\Delta C_D$ .

$$C_{D_2} = C_{D_1} + \Delta C_D = C_{D_1} + a_1 (C_{L_2} - C_{L_1}) + a_2 (C_{L_2}^2 - C_{L_1}^2)$$
 (8)

Now assume that

$$C_{D_2} = f(C_{D_1}, C_{L_1}, C_{L_2})$$
 (9)

Using the Taylor series method of error propagation:

$$S(C_{D_2}) = \{ \left[ \frac{\partial C_{D_2}}{\partial C_{D_1}} \right] + \left[ \frac{\partial C_{D_2}}{\partial C_{L_1}} \right] + \left[ \frac{\partial C_{D_2}}{\partial C_{L_2}} \right] + \left[ \frac{\partial C_{D_2$$

The partial derivatives in Equation (10) can easily be evaluated from the definition of  ${\rm C}_{{\rm D}_2}$  in Equation (8).

They are:

$$\frac{\partial C_{D_2}}{\partial C_{D_1}} = 1 \tag{11a}$$

$$\frac{\partial C_{D_2}}{\partial C_{L_1}} = - (a_1 + 2a_2 C_{L_1})$$
 (11b)

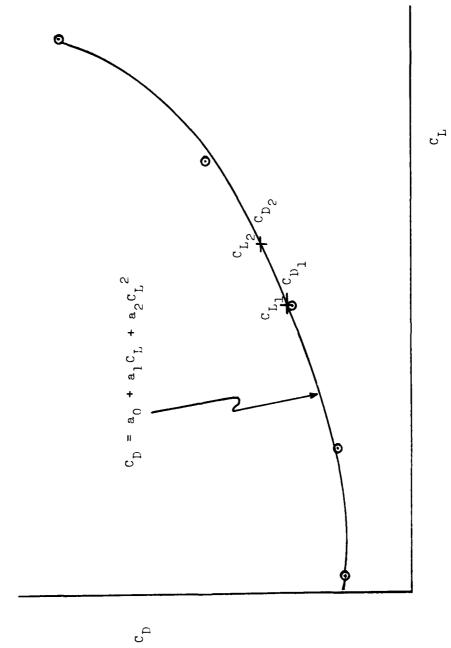


Figure 1. Example of  $C_{f L}$  Versus  $C_{f D}$  Data

$$\frac{\partial C_{D_2}}{\partial C_{L_2}} = a_1 + 2a_2 C_{L_2}$$
 (11c)

The terms  $S(C_{D_1})$ ,  $S(C_{L_1})$ , and  $S(C_{L_2})$  in Equation (10) require interpretation. They are the precision indices of  $C_D$  and  $C_L$  at point 1 and that of  $C_L$  at point 2. The  $C_L$  at point 2 is simply the desired flight condition. It can be thought of as a mathematical and not a random variable and can be exactly defined. Therefore:

$$S(C_{L_2}) = 0 (12)$$

 $C_{L_1}$  is a measured data point, and because of this, it is a random variable with a mean and standard deviation.  $S(C_{L_1})$  can be thought of as the uncertainty associated with the measurement process. If  $S(C_L)$  is constant or it changes slowly in the vicinity of the flight condition of interest,  $S(C_{L_1})$  should be a close approximation to the value that  $S(C_L)$  would have if  $C_{L_2}$  were a measured data point. Figure 2 indicates that  $S(C_L)$  does not vary much over the angle of attack range of interest ( $\alpha = 2 - 6^{\circ}$ ). Because of this,  $S(C_{L_1})$ , where  $C_{L_1}$  is the data point nearest the flight condition of interest, can be used to indicate the uncertainty associated with the measurement process. Calculation of  $S(C_L)$  is discussed in Section III.

Recall that the value of  $C_{D_1}$  used in Equation (8) to define  $C_{D_2}$  was not the measured value at  $C_{L_1}$ ; it was the value obtained from the curve fit equation. In other words:

$$C_{D_1} = a_0 + a_1 C_{L_1} + a_2 C_{L_1}^2$$
 (13)

Therefore,  $S(C_{D_1})$  is actually the precision index of  $C_{D_1}$ ,  $S^2$ , introduced by the curve fit process. A method for calculating  $S(C_{D_1})$  is found in Section IV.

Given the values of  $S(C_{L_1})$  and  $S(C_{D_1})$ , the final calculation of the uncertainty in  $C_D$  at a given flight condition can be performed as follows:

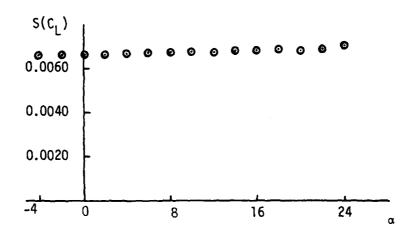


Figure 2. Precision Index of Lift Coefficient versus Angle of Attack M = 0.8

$$U(C_n) = t_n S$$
 (14)

 $t_n$  is the n<sup>th</sup> percentile point for the two tailed, student "t" distribution. Various percentiles or confidence levels can be chosen. The following discussion is based on a 95-percent confidence level. The ninety-fifth percentile point,  $t_{0.95}$ , depends on the number of degrees of freedom, which is a measure of the sample size used to determine the precision index. For  $S(C_{L_1})$ ,  $t_{0.95}$  is usually taken equal to 2 since  $S(C_L)$  is based on a large sample size. This value is not appropriate to use for  $S(C_D)$ . The Aircraft Compatibility Branch uses a five-point curve fit around the appropriate  $C_L$  to find  $C_D$ . For this case, the degrees of freedom are:

$$v = n - k - 1 = 2$$
 (15) where:

n - number of points used = 5

k - number of variables in regression equation = 2 (i.e.,  $C_L$ ,  $C_L^2$ ) For two degrees of freedom:

$$t_{0.95} = 4.303$$

The equation for uncertainty can be rewritten as:

$$U(C_{D}) = \{ [t_{0.95} C_{D_{1}}]^{2} + [t_{0.95} C_{C_{1}}]^{2} + [t_{0.95} C_{C_{1}}]^{2} \}^{\frac{1}{2}}$$
 (16a)

= 
$$\{4.303^2 \text{ S}(C_{D_1})^2 + 2^2[(a_1 + 2a_2 C_{L_1}) \text{ S}(C_{L_1})]^2\}^{\frac{1}{2}}$$
 (16b)

The value  $\mathrm{U}(\mathrm{C}_{\mathrm{D}})$  is the uncertainty in drag coefficient at a given flight condition for a given configuration. More important is the uncertainty in the drag increment between the clean aircraft and the aircraft with the external stores.

The increment is defined as:

$$\Delta C_{D} = C_{DStores} - C_{DClean}$$
 (17)

From Reference 1, the uncertainty is:

$$U(\Delta C_D) = \{U(C_{DStores})^2 + U(C_{DClean})^2\}^{\frac{1}{2}}$$
 (18)

#### SECTION III

#### DATA POINT PRECISION INDEX

Section II described a method to calculate drag data uncertainties for a point on a fitted  $C_L$ - $C_D$  curve. Because of the random nature of the assumed independent variable,  $C_L$ , the final calculation for  $U(C_D)$  requires a value for the precision index of  $C_1$ . This can be done in the following manner:

C, can be defined as:

$${}^{C}L = \frac{1}{QA} [FN (\cos \alpha \cos IM + \sin \alpha \sin IM)$$

$$+ FA (\cos \alpha \sin IM - \sin \alpha \cos IM)]$$
(19)

Ιf

$$C_1 = f(x_1, x_2, ..., x_n)$$
 (20)

then the Taylor series method of error propagation yields:

$$S(C_{L}) = \left\{ \left[ \frac{\partial C_{L}}{\partial x_{1}} S(x_{1}) \right]^{2} + \left[ \frac{\partial C_{L}}{\partial x_{2}} S(x_{2}) \right]^{2} + \dots + \left[ \frac{\partial C_{L}}{\partial x_{n}} S(x_{n}) \right]^{2} \right\}^{\frac{1}{2}}$$
(21)

It is apparent that the equations become more and more complex as the number of independent parameters increases. In addition, these variables must be independent or nearly so of each other for Equation (21) to hold. Assumptions need to be made on the nature of the measurements. These are:

- (1) The uncertainties associated with some of the independent parameters are sufficiently small that their effects on the uncertainty of the dependent parameter are negligible. This is assumed to be the case for IM and A.
  - (2) The measured forces, FN and FA, are independent of one another. Using these two assumptions, it can be said:

$$C_1 = f (FN, \alpha, FA, Q)$$
 (22)

Therefore:

$$S(C_L) = \left\{ \left[ \frac{\partial C_L}{\partial FN} - S(FN) \right]^2 + \left[ \frac{\partial C_L}{\partial \alpha} - S(\alpha) \right]^2 + \left[ \frac{\partial C_L}{\partial FA} - S(FA) \right]^2 + \left[ \frac{\partial C_L}{\partial Q} - S(Q) \right]^2 \right\}^{\frac{1}{2}}$$
 (2)

After evaluating the partial derivatives, Equation (23) may be rewritten as:

$$S(C_{L}) = \{ [(\cos \alpha \cos IM + \sin \alpha \sin IM) \frac{S(FN)}{QA}]^{2} + [C_{D} S(\alpha)]^{2} + [(\cos \alpha \sin IM - \sin \alpha \cos IM) \frac{S(FA)}{QA}]^{2} + [C_{L} \frac{S(Q)}{Q}]^{2} \}_{2}^{3}$$
 (24)

For a given test point,  $\alpha$ , IM, Q, A,  $C_D$ , and  $C_L$  are defined. S(FN), S(FA), S( $\alpha$ ), and S(Q) are functions of test conditions and instrumentation. Equations for these parameters can be developed in a manner similar to that used for Equation (24). S( $\alpha$ ) and S(Q) depend on the wind tunnel where the data are taken. S(FN) and S(FA) are dependent on the tunnel and model instrumentation. Equations to calculate the quantities for a specific case of interest should be obtained from the applicable test facility. The computer program described in Section V uses equations that apply to the Aerodynanmic Wind Tunnel (PWT/4T) at Arnold Engineering Development Center (AEDC).

#### SECTION IV

#### **CURVE FIT PRECISION INDEX**

A method to determine the precision index of  $C_L$  for use in Equation (16) was just described in Section III. The other input required to solve for  $U(C_D)$  is  $S(C_{D_1})$ . Recall that it was defined as the precision index of the curve fit process. To calculate this quantity, certain assumptions on the nature of the  $C_D$  data are made. These are:

- (1)  $C_D$  is a random variable.
- (2) At a given  $C_L$ , possible values of  $C_D$  are approximately normally distributed.
- (3) Over the  $C_L$  range where the curve fit is applied,  $S(C_D)$  is nearly constant. This allows a simplified curve fit procedure to be used (see pp 106-108, Reference 2).

Since it is possible to calculate  $S(C_D)$  for a given data point in a manner similar to that used for  $S(C_L)$ , the validity of the third assumption can be verified. Figure 3 shows a typical example. The angle of attack region of interest is about 2 to 6 degrees. As the figure indicates,  $S(C_D)$  does not vary significantly over this range.

Recall from Section II, the  $C_L - C_D$  curve is assumed to be of the form

$$C_D = a_0 + a_1 C_L + a_2 C_L^2$$
 (25)

For a second order curve fit, the normal equations to solve for  $a_0$ ,  $a_1$ ,  $a_2$  are, in matrix form:

[B] 
$$[a] = [g]$$
 (26)

where

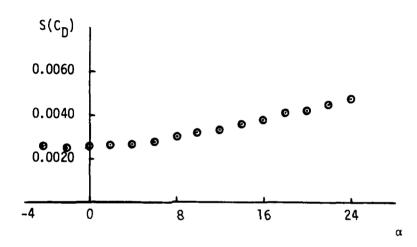


Figure 3. Precision Index of Drag Coefficient versus Angle of Attack M = 0.8

$$\begin{bmatrix} \mathbf{a} \end{bmatrix} = \begin{bmatrix} \mathbf{a}_0 \\ \mathbf{a}_1 \\ \mathbf{a}_2 \end{bmatrix} \tag{28}$$

Solution for the regression coefficients is given by:

$$[a] = [B]^{-1} [g]$$

Where  $[B]^{-1}$  is the inverse of [B]. For a five-point curve fit, n is equal to five.

In this study, the value of  $S(C_D)$  is based on the mean response  $\mu_{C_D|C_L,C_{L^2}}$ . The term  $\mu_{C_D|C_L,C_{L^2}}$  may be thought of as the true value of  $C_D$  for a given  $C_L$ . In other words, if many values of  $C_D$  were measured at a given  $C_L$ , the mean of  $C_D$  would tend to  $\mu_{C_D|C_L,C_{L^2}}$  as the sample size increased to infinity. Based on this,  $S(C_D)$  is defined as:

$$S(C_D) = \sqrt{[x_0^-][B]^{-1}[x_0^-]}$$
 (31)

where

S = estimated sample standard deviation

$$= \left[ \frac{\sum_{i=1}^{n} \left[ C_{D_i} - (a_0 + a_1 C_{L_i} + a_2 C_{L_i}^2) \right]^2}{n-k-1} \right]^{\frac{1}{2}}$$
 (32)

$$x_{o}^{-} = [1 \quad C_{L_{FC}} \quad C_{L_{FC}}^{2}]$$
 (33)

$$x_{o} = \begin{bmatrix} 1 \\ C_{L_{FC}} \\ C_{L_{FC}} \end{bmatrix}$$
 (34)

The FC subscript indicates the flight condition of interest where the calculation is made. For a more detailed discussion of the method used to calculate  $S(C_D)$ , see a statistics text such as Reference 3.

#### SECTION V

#### COMPUTER PROGRAM AND SAMPLE CALCULATION

Appendix A contains a computer program developed in the Aircraft Compatibility Branch to calculate uncertainties in drag coefficient where  $C_{\rm D}$  is found from a fitted  $C_{\rm L}$ - $C_{\rm D}$  curve. Required inputs are explained in the program. The uncertainty can be determined for confidence levels of 99, 95, 90, and 80 percent, i.e., x percent of measured data points should lie within the uncertainty band above and below the fitted curve. The confidence level is changed by using different t values as explained in Section II.

As noted earlier, the equations used to define  $S(C_L)$  are applicable to the four-foot transonic wind tunnel at AEDC. Changes would be required for other tunnels.

Assumptions are made to simplify the equations for  $S(C_1)$ . These include:

- (1) Only aircraft pitch excursions are considered, i.e.,  $\beta \approx 0$ .
- (2) Uncertainty in angle of attack is constant and equal to 0.1 degree.
- (3)  $S(\alpha)$  equals one half the uncertainty in  $\alpha$  (0.05 degree).
- (4) A small sting roll angle is assumed (0.04 degree).
- (5) Model weight does not vary between configurations.
- (6) To a first approximation, model angle of attack is equal to sting pitch angle.
- (7) Balance uncertainties [S(FNB), S(FAB)] are functions of normal and axial forces only (i.e., no side load or rolling moment interactions are present).
  - (8) There is no model roll angle relative to the balance.
- (9) The precision indices of model weight measured by axial and normal force gages are equal to the precision indices of the balance.
  - (10) Tunnel total pressure is less than 1500 lbs/ft<sup>2</sup>.
- (11) S(M) is constant and equal to 0.002 which is 40 percent of the uncertainty.

The assumptions are reasonable for the data of interest. Only pitch excursions are considered because the performance problem concerns mainly flight at a constant angle of attack.

Appendix A contains sample calculations of  $U(C_D)$  for a specific case. The example is for a clean aircraft at M=0.8 and  $C_L=0.3$ . If the equation for  $U(C_D)$  is examined using the values of  $S(C_D)$  and  $S(C_L)$  from the example, it shows that most of the uncertainty in  $C_D$  is a result of the curve fit. Note all the confidence levels are shown in the example, and  $U(C_D)$  decreases as the confidence level is lowered. To be more precise, the values S(FN), S(FA),  $S(\alpha)$ , and S(Q) used to find  $S(C_L)$  should be redefined for each confidence level instead of using the 95-percent values. Since the contribution of  $S(C_L)$  to  $U(C_D)$  is not large, this is not significant.

#### SECTION VI

#### CONCLUSIONS AND RECOMMENDATIONS

A method has been presented that shows how drag coefficient uncertainties can be calculated for wind tunnel data. Because of the need to examine  $C_D$  as a function of  $C_L$ , the uncertainties in  $C_D$  are due both to the uncertainties in  $C_L$  and those of the curve fit. While the method of calculating the precision index of the curve fit is general, that used to determine  $S(C_L)$  will depend on the wind tunnel and particular test instrumentation. Consultation with the applicable test facility will be necessary to work out suitable equations for  $S(C_L)$ .

The example given in Appendix A indicates that the uncertainty can be fairly large for a high confidence level. Reducing the confidence level results in a considerably smaller uncertainty. It would be very useful if data uncertainties associated with flight tests were given a thorough analysis. Determination of these uncertainties would increase the confidence in performance estimates based on flight test data.

#### REFERENCES

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- 3. Walpole, Ronald E. and Myers, Raymond H. "Probability and Statistics for Engineers and Scientists." The Macmillan Company, 1972.

## APPENDIX A

COMPUTER PROGRAM FOR UNCERTAINTY CALCULATION

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PROGRAM UNCERCINEUT. OUTPUT. TAPES = INPUT. TAPES = CUTPUT)
                                    CCCCX
                                                THIS PROGRAM CALCULATES THE UNCESTAINTY IN DRAG COEFFICIENT FOR A SPECIFIC FLIGHT CONDITION OF INTEREST ON A FITTED CL-CD DRAFT THE UNCESTAINTY IN CO IS MADE UP OF A COMBINATION OF UNCESTAINTY IN LIFT COEFFICIENT AND THE UNCESTAINTY INTRODUCED BY CURVE FITTING CL-CD DATA.
                                    13
                                                 THE FOLLOWING CONSTANTS ARE STORED IN BLOCKDATA.
                                                     PHII-ASSUMED STING POLL ANGLE DUPING A PITCH SHEEP (DEG)
SPHII-STANDARD DEVIATION OF STING FOLL ANGLE (DEG)
SL-CONSTANT PEPENDING ON PARTICULAP HIND TUNNEL
H-AIPCRAFT MODEL HEIGHT (LBS)
AS-A6-CONSTANTS USED TO ORTAIN STANDARD DEVIATION OF TUNNEL
TOTAL PEPSUBE. DEPENDS ON TUNNEL OF INTEREST.
SM-STANDARD DEVIATION OF MACH NUMBEP
SALPHA-STANDARD DEVIATION OF MACH NUMBEP
SALPHA-STANDARD DEVIATION OF ARGE OF ATTACK (RAD)
A1M-ANGLE PETHEEN AIPCRAFT HATER LINE AND BALANCE AXIS(DEG)
A-AIRCRAFT MODEL REFERENCE AREA (SO/FT)
A17-A16-CONSTANTS USED TO PETERMINE STANDARD DEVIATION OF
TUNNEL STING PITCH ANGLE. DEPENDS ON HIND TUNNEL.
X1.X2.X3.X9-RALANCE CONSTANTS
AK1.AK15.AK29-BALANCE CONSTANTS
CALLED K1.K15.K29)
SFANZ.FFANZ-RALANCE AND AXIAL LOAD RESPECTIVELY.
SFNNZ.SFNAZ-RALANCE NOPHAL FORCE GAGE UNCEPTAINTIES WITH
APPLIED NORMAL AND AXIAL FORCE.
15
2:
25
30
                                                 THE FOLLOWING VALUES APE CALCULATED FROM THE INPUT
                                                      SILPI-STANDARD DEVIATION OF STING PITCH ANGLE
SFA- " " AXIAL FORCE
SFO- " " NORMAL FORCE
SO- " " " YNAMIC PRESSURE
SCLTS- " " LIFT COFFFICIENT
35
47
                                                THE FOLLOWING INPUTS ARE FOR THE TEST POINT CLOSEST TO THE FLIGHT CONDITION OF INTEREST.
                                                     ALPHA-AIRCRAFT ANGLE OF ATTACK
AMACH-MACH NUMBER
OT-TUNNEL TOTAL PRESSURE
CLIS-LIFT COFFEICIENT
COTS-ORAS COFFEICIENT
POI-VALUE OF LIFT COFFFICIENT AT THE FLIGHT CONDITION
OF INTEREST.
45
E 1
                                                CONFT IS THE CONFIDENCE LEVEL SELECTED. VALUES OF .99. .95. .9. AND .8 ARE ALLOWED.
55
                                                 THE FIVE CL AND CO VALUES ARE THE ONES USED FOR THE CURVE FIT
                                                XC.XDP.9.G. AND AC AFE MATRICES USED TO OSTAIN REGRESSION CREFFICIENTS AND CALCULATE THE STANDARD DEVIATION DUE TO FIT
69
                                                AO,A1,A2 ARE THE RESRESSION CORRECTIONS CALCULATED FOR THE FITTED CURVE WHERE IT IS OF THE FORM

OD = A2 + A1*CL + A2*(CL**2)
                                                 SFITZ IS THE SQUARE OF THE STANDARD DEVIATION DUE TO CURVE FIT
                                                      COMMON/A/PHII.SPHII.SL.W.A5.A6.SM.SALPHA.AIM.A.A17.A18
COMMON/B/X9.4K15.SFANZ.SFAAZ
COMMON/C/X1.X2.X3.AK1.AK29.SFNN2.SFNAZ
COMMON/D/SALPI-SFA.SFN.SQ.SCLTS
COMMON/E/ALPHA.AMACH.PT-Q.CLTS.COTS.POI
COMMON/F/CL(5).CD(5).X0(3).X0P(3).B(3,3).G(3).AC(3)
71
```

75

-	PROGRAH UNCE	R 74/74 OPT=0 TRACE FIN 4.8+518
		COMMON/G/AU.A1.A2.SFITZ
		COMMON/G/AD.A1.A2.SFITZ COMMON/H/AD(1).AL(3).AM(3).Z(3).X(1) READ(5.1)ALPHA.AMACH-PT.Q.CLIS.CDTS.POI
	-1	FORMAT (7F1D.5)
80		IF (EOF (5)) 99, 3
	ě	READ (5.8) CONFI FORMAT (F10.5)
	<u> </u>	READ (5,2) (CL(1) .1=1.5) READ (5,2) (CD(1) .1=1.5) FORMAT (5,10.5)
85	2	FORMAT(5F10.5)
		CALL SOCL
	4.4	UDITER 44% AMACH
90	11	FORNAT (1H1, 13HMACH NUMBER =,F10.3) WRITE (6,12)
	12	FORMAT(///3x.23HMIND TUNNEL DATA POINTS) HRITE(6.13) (CL(1) = 1.5) FORMAT(/5x.26HVALUES OF LIFT COEFFICIENT/1H0.5F12.4) MRITE(6.14) (CD(1) = 1.5)
	13	MRITE(6,13) (GL(1),1=1,5) FORMAT(/5x.26HVALUES OF LIFT COFFFICIENT/1H0.5F12.4)
··· ·		WRITE(6,14) (CO(11,1=1,5)
95	14	FORMAT(/5%,26HVALUES OF DRAG COEFFICIENT/1H0,5F12.4)
-		FORMAT(/5x,26HVALUES OF DRAG COEFFICIENT/1H0,5F12.4) WRITE(6,15) POI FORMAT(//3x,30HLIFT COEFFICIENT OF INTEREST =,F10.4)
	7	WY 1 1 P CM = /   A    4 A   4 A
100		FÒRMĀT(///,1X,22MGŪRVE FIT COEFFICIENTS./.1H0.4X,4HAQ =,F12.5./ 1.5X,4HAI =,F12.5./.5X,4HA2 =,F12.5) MRITE(6,4) SCLTS
		WRITE(6.4) SCLTS FORMAT(//1x.26MSTANDARD_DEVIATION_IN_CL_=.F12.4)
		SETT=SOPT/SETT2)
-406		WRITE(6,5) SFIT
100	. •	CONF = CONF1 + 180 .
	16	WRITE (6.16) CONF
		IF(CONFILEQ.0.99) GO TO 100
110		### ### ##############################
	100-	TVAL 1=9.925
115_		TVAL 1=4, 303
	101	TVAL 1=4.303
		TVAL 2=2.
120	102	TVAL 1±2. Q2
460		TVAL 2=1.65 GO TO 200 TVAL 1=1.006
	103	TVAL 1=1.006
	200	TVAL 2=1.26 VAR1 = (TVAL 1 **2.) *SFIT2 VAR2 = (TVAL 2 **2.) * ((A1+2.*A2*CLTS)**2.)*(SCLTS**2.) UCD=SQRT (VAR1.*VAR2)
125		VAR2=(TVAL2++2.)+((A1+2.+A2+CLTS)++2.)+(SCLTS++2.)
		WRITE(6.6) UCD
	<u> </u>	FORMAT(///1x.37HTHE UNCERTAINTY IN DRAG COEFFICIENT =.F12.4)
138	99	STOP END
		END

1	Ç	
	SUBROUTINE SOCL	
. 5	C THIS SUBROUTINE CAL C LIFT COEFFICIENT	L <del>culates sclts, the standard deviation in</del> for the data point nearest the flight
	C CONDITION OF INT	
10	COMMON/A/PHII.SP	HII.SL.H.A5,A6.SM, SALPHA.AIM.A.A17.A18
	COMMON/C/X1.X2.X	3.4K1.4K29.SFNN2.SFNA2
	COMMON/D/SALPI,S	MACHEPTEGECLTSACOTSAPOT
15	SALPI=A17+A18+AL	PHA *2.+SFAA2**2.)**.5)
	SWA=SFAB SFAG2=(SL *X 9*AK1	
	SFAST2= LN+COSD (4)	LPHAITSÄLPIITTZ.+(SIND(ALPHAITSMAITTZ.
20	SFA= (SFAG2+SFĀST) SALPHA=. 000873	21**.5
<del>.</del>	SFNB=.5* ({SFNN2*	*2.+SFNA2**2.1**.5)
	SFNG2=((SL/X1)++; 1 +SFNB++2.	2.) + ( (X2*AK1) ++2.+ (X3+AK29) ++2.)
25	SWN=SFNB	
	VARINE (H*SIND (AL	PHA)*COSD(PHII)*SALPI)**2.
	VAR3N= (H#COSD (AL	PHA) +SIND (PHII) +SPHII) ++2.
36	SFNSTZ=VAR1N+VAR SFN <del>=\sfng2+</del> SF <del>nS</del> T	
30	VAR1P=(((2.+0/AH)	ÄCH)+(11.2+(AMACH++2.)))/
	1 (1.+.2*(AMACH*	*2.111*SH
	VAR2P= (Q/PT) *SPT	
35	SOE (VARIPERS. +VA	
	1 +SFN/(Q+A))++2	HĀ) *GŌSD (AÌM) +SIND (ALPHA) *SIND (AIM) )
	VAR2 T= (CDTS+SALP)	Ĥ#} ##2 <u>.                                      </u>
40	1 #SFA/(D#A)1##2	HÃ) *SĨŇO (AIM) -SINO (ALPHA) *COSO (AIM) )
-74	VARGT= (CLTS* (SG7)	Q1) **2.
	SCLTS=SQRT(VAR1T	÷VAR2T÷VAR3T+VAR4T)
	ENO	

	SUBROUTINE	SOFIT	74/74	0PT=0	TRACE		· · ··	· · FTN 4a	8+518
ì	<u> </u>	2		* -		<del></del>			· - <del></del>
		<u> </u>	SUBROUTINE S	DFIT			–		
5	5	Š · TH	IS SURROUTIN THE CL-CD DA THE CURVE FI	-	LAT <del>es t</del> Determi	HE REGRE	SSION COE STANDARD	FFICIENTS DEVIATION	10 FIT
10									
			COMMON/E/ALP COMMON/F/CL( COMMON/G/AT. COMMON/H/AD( SUM11=0. SUM21=0.	ATTAZIS	FIT2 ).AM(3)	.Z(3).X(	1)	·····	
15	). 								
20	. <u>.</u>		SUM3 1=0 .  SUM3 1=0 .  SUM4 1=0 .  SUM4 1=0 .  SUM1 1=1 .  SUM1 1=SUM2 1 .  SUM3 1=SUM3 1 .  SUM3 2=0 .  SUM3 1 .  SUM3	CL (I) CL (I) **	2.				
		10	SUM41=SUM41+ CONTINUE	CL (I) **	4: 				
25	·		B(1,1)=7. B(1,2)=SUM11 B(1,3)=SUM21						
30	<b>)</b>		8(2,1)=SUM11 8(2,2)=SUM21 8(2,3)=SUM31 8(3,1)=SUM31						
35			5 (3.3) = SUM41 SUM1 2=0. SUM2 2=0. SUM3 2=0.						
_ 40	)	25	DO 20 I=1,5 SUM12=SUM12+ SUM22=SUM22+ SUM32=SUM32+ CONTINUE	CF ([])*C	5.*CD(I	)			
45			Ğ(1)=SUM12 G(2)=SUM22 Ğ(3)=SUM32 CALL MINV(B,	3, AD, AL	 • AH)				
		Ć CA	LL TO SYSTEM	ROUTIN	E TO IN	VERT HAT	RIX B		
50	_	3	CALL GMPRD(B Ltiply inver AG=AC(1) A1=AC(2)			O OSTAIN	MATRIX A	·c	
59	5	1	LTIPLY INVER AG = A C(1) A1 = A C(2) A2 = A C(3) A2 = A C(3) B0 30 I = 1.5 SUM3 = SUM3 + (C E = E 2.5 COMITMUE SSD = SUM3 / 2.5 X0P(1) = 1.5 X0P(1) = 1.5 X0P(3) = POI = 4.5 X0P(3) = POI = 4.5 D0 40 I = 1.3	0 <b>( T ) - A</b> O	-A1*CL(	11-42*(0		,	
61	)	30	CONT INUE SSD=SUM3/2. XOP(1)=1.						
- 69		40	X0P(3)=P01** 00 60 1=1.3 X0(1)=X0P(1) CONTINUE CALL GMPRD(X	2. DP-8-7-	1.3.31				
-7(		Č MU	LTIPLY XOP B	Y INVER	SE OF B	TO OBTA			
71		HU E	ETTPLY Z RY Matrix. The Standard dev	VALUE I	BTAIN X S MULTI TO OBTA	PLIED BY	THE SQUARE OF	INN ONE ROLLE OF THE	SAMPLE

SUBROUTINE SOFIT 74/74 OPT=8 TRACE FYN 4.8+518

C DEVIATION DUE TO CURVE FIT.

C X1=X (1) SFIT2=SSD+X1
RETURN
END

BLOCK DAT	TA BLKOAT. 74/74 OPT=B TRACE	
	BLOCKUATA COMMON/A/PHII.SPHII.SL.M.A5.A6.SM.SALPHA. COMMON/B/X9.AK15.SFANZ.SFAAZ	AIM.A.A17.A18
5	ARMANIARIUA WA UR ENA EURA CENNO CENNO CENNO	
·	CUMPUT/C/A1, X2, X3, ARI, ARC 9.5 R (SALPHA, AIM, DATA PHII, SPHII, SL, 94, 86, 5 R (SALPHA, AIM, 100, 100, 100, 100, 100, 100, 100, 10	1.0.
10	DATA X1.X2,X3.AK1.AK29.SFNNZ.SFNAZ/3.912. 1 .39339948976/	-1.,1.,

MACH NUMBER -	·· •799·····			
HIND TUNNEL DATA	POINTS		and the state of t	
VALUES OF LIFT	COEFFICIE	NT		
· · · · · · · · · · · · · · · · · · ·	· •17 <del>70</del> -	.3324	. 4925	
VALUES OF DRAC	COEFFICIE	NT		
.0152	.0169	-0272	. 0468	. 0.80 %
LIFT-COEFFICIENT				- 4 6 0 0
				- 4 60 3
CURVE FIT COEFFICE	ENTS			- 4 60 3
	ENTS			. 1 00 0
CURVE FIT COEFFICE	ENTS 584 506 597	ST =31	000	
CURVE FIT COEFFICE A0 = .016 A1 =046 A2 = .225	ENTS 584 506 597	ST =31	300	

HACH NUMBER =	• 199			
WIND TUNNEL DATA	POINTS		······································	
VALUES OF LIFT	COEFFICIF	NT	· · · · · · · · · · · · · · · · · · ·	<del></del>
	•1770 ···		4925	-6374
VALUES OF DRAG	COEFFICIE	NT		
.0152	.0169	.0272	.0468	.0803
CURVE FIT COEFFICE		ST- =31	DO3	
CURVE FIT COEFFICE	CENTS	ST- =	<del></del>	
CURVE FIT COEFFICE	CENTS	S T- =31	703	
AO = .010	LENTS 684 606		703	
CURVE FIT COEFFICE  A0 = .01( A1 =04) A2 = .22(	IENTS 684 606 597 N IN CL =	.0033		

WIND TUNNEL DA	TA POINTS			
VALUES OF LI	FT COEFFICIE	NT		
0231		- 3324	. 4925	.6374
VALUES OF DR	AG COEFFICIE	NT		~ <del>~~~</del>
.0152	.0169	.0272	.0468	.0803
	CIENTS	ST = ,-3:	000	
CURVE FIT COEFFI	CIENTS	ST-=3	000	
CURVE FIT COEFFI	CIENTS	ST-=3	900	
CURVE FIT COEFFICATION OF THE PROPERTY OF T	CIENTS 1684 4606 2597		000	
CURVE FIT COEFFI	CIENTS 1684 4606 2597	•0033	000	

HACH NUMBER =	799		· · · · · · · · · · · · · · · · · · ·	······································
WIND TUNNEL DATA	POINTS			
VALUES OF LIFT	COEFFICIENT			
	-1770	3324	• 4925	-6374
VALUES OF DRAG	COEFFICIENT	<del> </del>		
.0152	.0169	.0272	.0468	.0803
LIFT COEFFICIENT		= .31	000	
		- 31	000	
CURVE FIT COEFFICIA A0 = .0166 A1 =046	ENTS 84		000	
CURVE FIT COEFFICIA	ENTS 84	- 3	008	
CURVE FIT COEFFICIA A0 = .016 A1 =046	ENTS 84 16		000	
CURVE FIT COEFFICIA A0 = .016 A1 =046 A2 = .225	ENTS 84 96 97	.0033	000	

